

1 Not all speed-accuracy tradeoff manipulations have the same psychological effect

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Abstract

1
2 In many domains of psychological research, decisions are subject to a speed-accuracy trade-
3 off: faster responses are more often incorrect. This trade-off makes it difficult to focus on one
4 outcome measure in isolation – response time *or* accuracy. Here, we show that the
5 distribution of choices and response times depends on specific task instructions. In three
6 experiments, we show that the speed-accuracy trade-off function differs between two
7 commonly-used methods of manipulating the speed-accuracy trade-off: Instructional cues
8 that emphasize decision speed or accuracy, and the presence or absence of experimenter-
9 imposed response deadlines. The differences observed in behavior were driven by different
10 latent component processes of the popular diffusion decision model of choice response time:
11 instructional cues affected the response threshold and deadlines affected the rate of decrease
12 of that threshold. These analyses support the notion of an “urgency” signal that influences
13 decision making under some time-critical conditions, but not others.

1 Not all speed-accuracy tradeoffs have the same psychological effect¹

2
3 **Keywords:** Diffusion Decision Model, decision-making, time pressure, decreasing thresholds

4 5 **1. Introduction**

6 Decision making has been a focus of psychological research for decades. In many decision-
7 making contexts time pressure is of critical importance. A well-studied decision outcome of
8 time pressure is the *speed-accuracy trade-off* (SAT): a decision-maker can improve the
9 accuracy of their decisions at the expense of taking longer to respond, or they can make very
10 quick decisions that are more likely to be erroneous (Schouten & Bekker, 1967; Wickelgren,
11 1977). This pattern of results produces the trade-off between speed and accuracy, and it is the
12 task of the decision-maker to balance the relationship between accuracy and speed to achieve
13 their desired level of performance (cf. Bogacz, Brown, Moehlis, Holmes, & Cohen, 2006).

14
15 A range of experimental manipulations have been used to elicit the SAT in previous research
16 (see Heitz, 2014 for an overview). Cue-based SAT is arguably the most frequently used
17 speed-accuracy manipulation. The cues are typically verbal prompts instructing participants
18 to focus on responding correctly or responding speedily (Hale, 1969; Howell & Kreidler,
19 1963). Another common SAT manipulation uses response deadlines (Ratcliff & Rouder,
20 2000; Van Zandt, Colonius, & Proctor, 2000). Response deadlines usually involve a visual or
21 auditory message following each trial if the participant did not respond sufficiently fast. In
22 most cases, the deadline is pre-specified by the experimenter. Recently, some authors have
23 combined the two SAT manipulations into one design (e.g., Forstmann et al., 2008; Mulder et
24 al., 2013; Wagenmakers et al., 2008). Although both manipulations produce a manifest SAT
25 in behavioral data,² we hypothesize that the cognitive processes invoked by the two
26 manipulations differ. In the current paper, we test this hypothesis in three experiments, and
27 show that choices and response times differ between cue-induced SAT conditions and
28 deadline-induced SAT conditions. We also show that these differences can be attributed to
29 different latent component processes of the popular Diffusion Decision model (DDM) of

¹ Code for the models and data are provided at OSF: <https://osf.io/r7dzv/>

² SAT refers here to the empirical phenomenon of lower accuracy when speed is emphasized (and vice versa). This is not to be confused with the use of SAT to describe the latent psychological mechanisms that underlie or cause the observed pattern in data.

1 choice response time (Forstmann, Ratcliff, & Wagenmakers, 2016; Ratcliff, 1978; Ratcliff &
2 McKoon, 2008; Ratcliff & Rouder, 1998).

3

4 A standard practice in perceptual decision-making research has been the application of
5 sequential sampling models, also known as evidence accumulation models, to draw
6 inferences about the cognitive processing mechanisms underlying decision-making
7 (Forstmann et al., 2016; Gold & Shadlen, 2007; Mulder, van Maanen, & Forstmann, 2014;
8 Ratcliff & McKoon, 2008; Ratcliff, Smith, Brown, & McKoon, 2016).³ These models
9 hypothesize that decisions involve accumulation of sensory information in favor or against
10 certain choices at hand. Accumulation stops when enough information has been collected to
11 support some specific choice. The stopping point represents the uncertainty that the decision
12 maker is willing to accept on the correctness for this particular choice: more lenient stopping
13 points correspond to greater uncertainty.

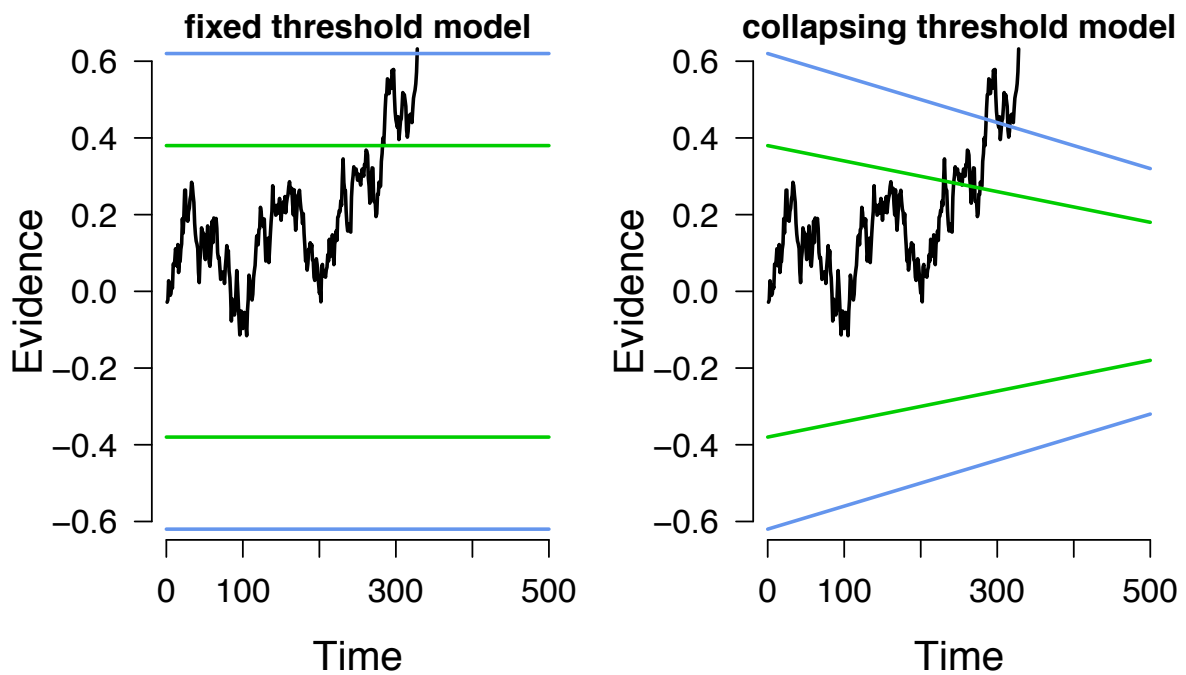
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15 Within the class of sequential sampling models, the DDM (Ratcliff, 1978; Ratcliff &
16 McKoon, 2008) is an important tool for isolating and understanding the cognitive processes
17 that underlie decision behavior, because of its demonstrated ability to provide a quantitatively
18 precise account of the response time (RT) distributions of correct/error responses in two-
19 alternative forced choice tasks (Ratcliff & McKoon, 2008; Ratcliff & Rouder, 1998; Ratcliff
20 & Smith, 2004; Ratcliff et al., 2016) . To account for time pressure in decision-making, the
21 DDM assumes a set of two thresholds, one for each of the possible response options (Figure
22 1, left panel). The decision maker's willingness to commit to decisions with greater
23 uncertainty is translated into thresholds that are close to the starting point of the accumulation
24 process (green lines). This response regime means that the accumulation process often
25 reaches one of the two thresholds before much accumulation has even taken place; this leads
26 to fast responses that are often erroneous. Conversely, thresholds that sit further from the
27 starting point (blue lines) represent a more conservative decision strategy whereby the
28 decision maker accumulates a greater amount of evidence before committing to a decision;
29 this leads to slower but more accurate responses. Such changes between low and high
30 thresholds have provided a good explanation of SAT behavior across a range of contexts
31 (Bogacz, Wagenmakers, Forstmann, & Nieuwenhuis, 2010; Forstmann et al., 2008; Ratcliff

³ Similar models have also been used to explain preferential decision-making (e.g., Bhatia, 2013; Busemeyer, Gluth, Rieskamp, & Turner, 2019; Roe, Busemeyer, & Townsend, 2001; Trueblood, Brown, & Heathcote, 2014; Turner, Schley, Muller, & Tsetsos, 2018).

1 & McKoon, 2008; Ratcliff & Rouder, 1998; Voss, Rothermund, & Voss, 2004;
 2 Wagenmakers et al., 2008), although the link between the computational description of SAT
 3 and its low-level neural implementation is still a matter of active research (e.g., Heitz &
 4 Schall, 2012; Reppert, Servant, Heitz, & Schall, 2018).

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8 *Figure 1. Different assumptions in diffusion models. Left panel: the standard Diffusion*
 9 *Decision Model (DDM) assumes thresholds that are fixed throughout the course of a decision*
 10 *and only vary with respect to the distance between lower and upper threshold. Green*
 11 *thresholds indicate a speedy response regime, blue thresholds indicate a more accurate*
 12 *response regime. Right panel: DDM with collapsing thresholds where the slope indicates the*
 13 *amount of evidence required to make a decision as a function of elapsed decision time, and*
 14 *distance between the thresholds at time 0 indicates the initial response caution.*

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16 In contrast to the fixed-threshold adjustment explanation of the cue-used SAT, Frazier and
 17 Yu (2008), Cisek et al. (2009) and Thura et al. (2012) gave different but converging
 18 explanations about the cognitive processes involved when decision-makers are faced with
 19 deadlines (see also Malhotra, Leslie, Ludwig, & Bogacz, 2017). According to Frazier and Yu
 20 (2008), a stopping rule in the form of thresholds that dynamically move toward one another
 21 (decline) throughout the course of a decision provides a mechanism that ensures the decision-
 22 maker responds before a deadline, whether that deadline is internally or externally imposed,

1 in the most efficient way (Figure 1, right panel). Frazier and Yu (2008) argue that in the
2 presence of response deadlines, thresholds that monotonically and non-linearly collapse over
3 time are the optimal decision-making strategy (i.e., the decision policy that maximizes reward
4 over a series of trials). In a similar vein, Cisek et al. and Thura et al. proposed a decision-
5 making model that incorporated an urgency signal that increases with elapsed decision time;
6 this can be viewed as an internally imposed deadline, as the urgency signal monotonically
7 increases the probability of committing to a choice as decision time increases.⁴

8
9 Given that the collapsing thresholds and urgency signal models on the one hand, and DDMs
10 with fixed thresholds on the other, make different quantitative behavioral predictions about
11 choice and RT distributions (for a review see Hawkins, Wagenmakers, Ratcliff, & Brown,
12 2015), the empirical validity of these contrasting theoretical accounts have been
13 systematically studied by a variety of researchers (Evans, Hawkins, Boehm, Wagenmakers,
14 & Brown, 2017; Ratcliff & Smith, 2004; Van Zandt et al., 2000; Winkel, Keuken, van
15 Maanen, Wagenmakers, & Forstmann, 2014). Although previous research has shed light on
16 the way deadlines and cues affect core empirical measures of decision-making, such as the
17 shape of RT distributions, and how these may be attributed to different psychological
18 processes (Evans, Hawkins, & Brown, in press), to our knowledge the empirical effects of
19 cue-based and deadline-based manipulations of the SAT have not been directly compared
20 within the same experimental design. Such a direct comparison would make it possible to
21 control for both SAT manipulations (cue, deadline) and to generalize their effects across
22 different tasks. Furthermore, directly comparing these manipulations within the same design
23 would allow us to propose a model-based account for the differential effects of the two SAT
24 manipulations on the choice-RT distributions. This will contribute to the debate surrounding
25 the nature of response thresholds (fixed vs. decreasing) in evidence accumulation models of
26 decision making under time pressure.

27
28 To that goal, we performed three behavioral experiments that each factorially crossed cue-
29 based and deadline-based manipulations of the SAT in a within-subject design to determine
30 whether they led to differential effects on observed choices and response times. Our central
31 aim was to examine the cognitive processes that distinguish performance in cue-based and

⁴ Beyond the SAT, collapsing thresholds might arise for different reasons. For example, there may be limited capacity for evidence to become saturated over time, as in recognition decisions (e.g., Cox & Shiffrin, 2017).

1 deadline-based SAT manipulations (section 5). In particular, we accounted for decision
2 processes in terms of evidence accumulation, where the threshold of the accumulation
3 process was expected to discriminate between the two forms of SAT manipulation, by
4 attributing the differential effects of cues and deadlines to distinct components of strategic
5 adjustments to response caution. Our analyses included a systematic model comparison of
6 DDMs with fixed and decreasing threshold parametrizations encoding different ways of
7 adjusting response caution to establish which adjustment mechanisms better explain decision
8 processes under different forms of time pressure.

11 **2. Methods**

12 **2.1. Participants**

13 Twenty-four participants affiliated with the University of Amsterdam participated in
14 Experiments 1 and 2 (mean age = 23.45, SD age = 7.86, 58% female) in the same
15 experimental session. A different sample of twenty-four participants affiliated with the
16 University of Amsterdam participated in Experiment 3 (mean age = 22.75, SD age = 3.40,
17 62% female). All participants provided informed consent prior to participation and chose
18 between a monetary or research credit reward at will.

21 **2.2. Design and Procedure**

22 **2.2.1. Experiment 1**

23 Participants made motion direction judgments about random-dot kinematograms (Ball &
24 Sekuler, 1982). In a random dot motion task participants are presented with a cloud of dots, a
25 subset of which move coherently in a particular direction while the remaining dots move in
26 random directions. The participant's task is to determine the direction of the coherently
27 moving dots. The experiment was implemented with the default version of the *Random dot*
28 *motion task* in Psychopy (Peirce, 2007) for which the default Random Dot Kinematic
29 component was used (Scase, Braddick, & Raymond, 1996). The settings were: dot life-time
30 of 5 frames, dot size of 4 pixels, cloud-size of 400 dots and speed of dots of 0.5% of monitor
31 dimensions per frame and the so-called "position" movement algorithm from Psychopy. The
32 experiment was conducted on a desktop computer with stimuli presented on a 21-inch
33 monitor set at 60Hz frame rate.

1 The task consisted of two phases: training and test. The aim of the training phase was to
 2 familiarize participants with the task and to establish settings for the test phase. Task
 3 instructions were provided on screen with participants briefly introduced to the structure of
 4 the task and given instructions to focus on the accuracy of their responses. Keyboard keys
 5 were used to make a response (“f” to indicate the dots move left, to the “j” to indicate dots
 6 move to the right). A trial finished with the participant’s response and feedback was given
 7 based on response accuracy.

8

9 In the training phase participants made decisions across 6 difficulty levels where difficulty
 10 was manipulated by changing the percentage of coherently moving dots: 3%, 7%, 11%, 15%,
 11 19%, and 23%. There were 40 trials for each difficulty level for a total of 240 trials.
 12 Following completion of the training phase, a single difficulty level was selected separately
 13 for each participant for use in their test phase. This value was selected as the lowest motion
 14 coherence at which a participant scored above 80% in the training session.

15

16 The test phase had a 2x2 within-subjects design. The first factor was whether participants
 17 were cued to respond fast or accurately. The second factor was whether there was a response
 18 deadline (i.e., an upper limit on the available decision time) or not. This produced four
 19 conditions in the experiment: speed cue with deadline, speed cue without deadline, accuracy
 20 cue with deadline, and accuracy cue without deadline. The four conditions were presented in
 21 separate blocks with block order counterbalanced across participants. Table 1 shows the task
 22 instructions given at the beginning of each block for the four conditions. There were 200
 23 trials in each of the 4 conditions/blocks for a total of 800 trials in the test phase.

24

25 *Table 1. Instructions and feedback given to participants in the test phase.*

Factor	Level	Instruction	Feedback
Cue	Speed	“Focus on being as speedy as possible”	“Good time!” (if fast enough) OR “Faster!” (if too slow)
	Accuracy	“Focus on giving as many accurate responses as possible”	“Correct!” (correct) OR “Be more accurate!” (incorrect)
Deadline	Deadline	“Strict deadlines will apply”	“You missed the deadline!”

		(no response before deadline)
No deadline	“There will be no deadline for your answer”	(nil)

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The cue-based SAT manipulation was operationalized by giving instructions prior to each block (Table 1). The deadline manipulation was operationalized as a trial cut-off at 1.35 sec, which was selected based on pilot data. If a response had not been registered by the time of the deadline then the stimulus was removed from the display and responses were no longer accepted. No trial cut-off was present in blocks without deadlines.

The pre-stimulus period (fixation cross, 250ms) directed focus to the center of the screen, after which the stimulus was presented. The stimulus duration then depended on the condition. In the no-deadline condition, the stimulus remained on the screen until the participant gave a response. In the deadline condition, the stimulus was presented at most for 1.35sec, which was the deadline cut-off. If participants missed the deadline, the trial was terminated immediately. Otherwise, by giving a response, the participant ended the trial.

To increase the likelihood that participants followed the block-based instructions they received feedback following each trial tailored to the pair of conditions in the current block. The text that was given as feedback is shown in Table 1. In the deadline condition, feedback was based on whether the response was prior to the deadline or not. In the condition without a deadline there was no feedback. In the accuracy cue condition, the feedback focused on whether the response was correct or not. In the speed cue condition, to ensure that participants did not associate feedback related to the cue with a specific cut-off value (i.e., as a deadline) we used a probabilistic feedback method. The feedback stated whether the response was fast or not fast. The probability of “not fast” feedback increased with the trial RT, according to a cumulative Gamma distribution fit to each participant’s RT data from the training phase. Thus, the slower a response, the more likely it was the participant would receive “not fast” feedback, but in an individualized fashion. Because feedback was probabilistic, there was no duration after which participants were guaranteed to receive “not fast” feedback, which would essentially implement a response deadline. For all conditions the

1 feedback duration varied with respect to being positive or negative; positive feedback was
2 shown for 250ms and negative feedback was shown for 1sec.

3 4 **2.2.2. Experiment 2**

5 To generalize the results of Experiment 1 to a different decision environment, we used a
6 rapid expanded judgment task where participants were presented with two flashing circles
7 and they were asked which of the two circles has the higher flashing rate (cf. Brown,
8 Steyvers, & Wagenmakers, 2009; Hawkins, Brown, Steyvers, & Wagenmakers, 2012; Smith
9 & Vickers, 1989); we refer to this as the *Flash Task*. The Flash Task externalizes to the
10 stimulus display a discrete and explicit evidence process, which we assume gives rise to a
11 corresponding internal evidence accumulation process. This contrasts to the internalized
12 evidence accumulation process that is assumed in most perceptual decision making tasks,
13 such as random dot motion in Experiment 1 (for a discussion of the differences, see Ratcliff
14 et al., 2016). The flash and random dot motion tasks necessarily draw upon different
15 perceptual processes, because the perceptual display qualitatively differs between tasks, yet
16 this is not to say that the two tasks lead to different cognitive processes including (but not
17 limited to) strategic adjustments to response caution.

18
19 All details of the flash task in Experiment 2 were the same as the random dot motion task in
20 Experiment 1 with the exception of the manipulation of difficulty. There were 6 difficulty
21 levels: 55% - 45%, 60% - 40%, 65% - 35%, 70% - 30%, 75% - 25% and 80% - 20%
22 frequency rate, where the percentage indicates the probability of a circle flashing on each
23 frame rate of the task, and the first percentage represents the rate of one circle and the second
24 of the other. The 6 difficulty levels and the circle with the faster flash rate (left or right) was
25 randomized for each trial. As in Experiment 1, the difficulty level for the test phase was
26 selected as the smallest difference in flash rate at which a participant scored above 80% in the
27 training session.

28 29 **2.2.3. Experiment 3**

30 As we show below (see Results), the deadline used in Experiment 2 might have been too
31 slow; few responses in the deadline condition cell received “you missed the deadline!”
32 feedback, suggesting participants did not actually experience the time pressure of a response
33 deadline. To address this concern, in Experiment 3 we modified the flash task to include an
34 additional earlier deadline. The experiment had a 2x3 within-subjects design with two levels

1 for cue-based SAT and 3 levels for deadline-based SAT (early, late and no deadline). The late
2 deadline was set equal to the deadline in Experiment 2, namely 1.35s, while the early
3 deadline was set at 683ms. The early deadline was selected as the 75% percentile of the
4 aggregate RT distribution in the deadline conditions from Experiment 2. The additional
5 deadline achieved two goals: to set a deadline that would be early enough to induce the
6 experience of a response deadline in the flash task but not so early as to induce chance-level
7 accuracy, and to replicate and extend the findings of Experiment 2.

8
9 Most of the presentation settings were retained from Experiment 2, with the following
10 exceptions. The number of training trials was reduced to 30. A lower difficulty level was
11 selected during the training period to make the task easier since it had been found too
12 difficult in Experiment 2. The level of difficulty selected for each participant was the hardest
13 one at which they scored more than 90% during the training phase. The task was
14 counterbalanced and all participants saw all combinations of conditions. The combinatorial
15 method used was Latin-Graeco square, because of the difficulty of presenting all possible
16 permutations to all participants. To keep the duration of Experiment 3 similar to the duration
17 of Experiments 1-2, the number of trials was initially set to 150 for each of the 6 blocks.
18 After the first 5 participants had participated it was clear that the experiment was too long.
19 For that reason, the rest of the participants were tested for 130 trials per block (780 trials in
20 total).

21
22 The instructions were as described in Experiment 1 and 2 with the exception of the new
23 conditions. Unlike Experiment 1 and 2 which provided accuracy feedback only in accuracy
24 conditions, we generalized accuracy feedback for every trial. This was done to ensure the
25 increase of the overall level of performance. The RT comparison procedures and feedback
26 text were as described in the previous two experiments.

27 28 **3. Results and Discussion**

29 We present the statistical results combined across experiments in text; E1-3 denotes
30 Experiments 1-3. Descriptive statistics for mean RT and accuracy are shown in Table 2.

31
32 *Table 2. Mean response time (RT) and accuracy in Experiments 1-3, including standard*
33 *error of the mean (SE).*

Experiment	Cue	Deadline	Mean, ms (SE)	Accuracy (SE)
1	Accuracy	No	784 (34)	0.89 (0.01)
		Yes	564 (10)	0.84 (0.02)
	Speed	No	571 (16)	0.78 (0.02)
		Yes	494 (10)	0.72 (0.02)
2	Accuracy	No	1248 (47)	0.77 (0.03)
		Yes	623 (14)	0.69 (0.03)
	Speed	No	514 (15)	0.64 (0.03)
		Yes	473 (11)	0.63 (0.03)
3	Accuracy	No	909 (35)	0.85 (0.03)
		Late	613 (15)	0.76 (0.04)
		Early	449 (9)	0.70 (0.04)
	Speed	No	647 (21)	0.76 (0.03)
		Late	522 (13)	0.74 (0.04)
		Early	423 (9)	0.68 (0.04)

1

2 Mean RT was significantly faster in trials with deadlines than trials without deadlines (E1 -
3 $F(1,23)=22.14$, $p<0.001$, $\eta_G^2=0.09$; E2 - $F(1,23)=16.66$, $p<0.001$, $\eta_G^2=0.12$; E3 -
4 $F(2,46)=72.77$, $p<0.001$, $\eta_G^2=0.43$).⁵ Mean RT was also faster in speed-focused relative to
5 accuracy-focused trials (E1 - $F(1,23)=18.42$, $p<0.001$, $\eta_G^2=0.08$; E2 - $F(1,23)=29.13$,
6 $p<0.001$, $\eta_G^2=0.19$; E3 - $F(1,23)=27.95$, $p<0.001$, $\eta_G^2=0.13$). There was a significant
7 interaction between the cue-based and deadline-based manipulation on mean RT (E1 -
8 $F(1,23)=8.89$, $p=0.006$, $\eta_G^2=0.02$; E2 - $F(1,23)=13.86$, $p<0.001$, $\eta_G^2=0.09$; E3 -
9 $F(2,46)=10.91$, $p<0.001$, $\eta_G^2=0.09$). In each experiment, the interaction was due to responses
10 showing greater speeding from the no-deadline to the deadline conditions in the “accuracy”
11 regime as opposed to the “speed” regime.

12

13 Accuracy was significantly greater in trials without deadlines compared to trials with
14 deadlines (E1 - $F(1,23)=14.87$, $p<0.001$, $\eta_G^2=0.04$; E2 - $F(1,23)=14.36$, $p<0.001$, $\eta_G^2=0.04$; E3
15 - $F(2,46)=58.93$, $p<0.001$, $\eta_G^2=0.30$). Accuracy was also significantly greater in accuracy-
16 focused trials compared to speed-focused trials (E1 - $F(1,23)=18.30$, $p<0.001$, $\eta_G^2=0.16$; E2 -

⁵ Throughout the text we use Bayesian analysis to support claims of no effect established by frequentist statistics.

1 $F(1,23)=41.83$, $p<0.001$, $\eta_G^2=0.20$; E3 - $F(1,23)=20.81$, $p<0.001$, $\eta_G^2=0.08$). There was a
2 significant interaction between the cue-based and deadline-based manipulation on accuracy
3 in Experiments 2 and 3 (E2 - $F(1,23)=10.54$, $p<0.003$, $\eta_G^2=0.04$; E3 - $F(2,46)=8.81$, $p<0.001$,
4 $\eta_G^2=0.04$). The nature of the interaction on choice accuracy was similar to the interaction on
5 RT: accuracy decreased to a larger degree between the no-deadline to the deadline conditions
6 when given accuracy-emphasis cues compared to speed-emphasis cues. The interaction was
7 not significant in Experiment 1 ($F(1,23)=0.17$, $p=0.678$, $\eta_G^2<0.01$; $BF_{10} = 0.29$), suggesting
8 that the interaction between speed-accuracy tradeoff manipulations on decision accuracy may
9 be dependent on the decision task (random dot motion task vs flash task).

10

11 The analysis of mean RT and accuracy confirm that a SAT was induced in each experiment:
12 participants were able to make faster decisions at the expense of more errors. These results
13 were consistent across two types of perceptual decision-making task: one where evidence
14 accumulated in discrete fashion (the flash task; Experiments 2 and 3) and another where
15 evidence accumulated in a continuous fashion (the random-dot motion task; Experiment 1).

16 As expected, both deadline-based and cue-based manipulations of time-pressure induced a
17 SAT, consistent with previous studies on time pressure. Stricter deadlines lowered choice
18 accuracy and mean RT. Furthermore, the presence of response deadlines in the accuracy-
19 focused conditions produced a larger SAT effect than those in speed-focused conditions, as
20 indicated by the interaction between the two manipulations.⁶

21

22 The stable interaction pattern between cue-based and deadline-based manipulations of the
23 SAT suggests that different latent components of processing may have driven the effects
24 observed in data. In the next section we argue that cue-based manipulations affect the overall
25 level of cautiousness (initial threshold in Figure 1) while deadlines influence moment-to-

⁶ Although the two SAT manipulations showed similar patterns across the two tasks, it is worth noting the discrepancies between experiments. Generally, the Flash task was more difficult than the random dot motion task, as indicated by higher error rates, especially in the speed-focused trials where the presence of the deadline did not change the effect size of performance accuracy in speed-focused trials (cf. Table 2). We took this as an indication that, in Experiment 2, the feedback related to the speed cue was perceived as a deadline, potentially canceling or ‘blocking’ the effect of the deadline manipulation. By generalizing the feedback to all conditions in Experiment 3 and reducing overall task difficulty, we observed an effect of the early deadline on the SAT in Experiment 3, consistent with the results of Experiment 1.

1 moment adjustments to response caution. We will use the popular Diffusion Decision Model
2 (DDM) to test this hypothesis and contrast it to alternative hypotheses.

3 4 **4. Cognitive modeling of the differential effects of deadline-based and cue-based SAT** 5 **manipulations**

6
7 In Experiments 1-3 we observed that the presence and the strictness of response deadlines
8 during decision making affect mean RT and accuracy. Though both cue-based and deadline-
9 based manipulations led to a trade-off between speed and accuracy, in this section we test
10 whether the two manipulations invoked different cognitive processes. We interpret the
11 behavioral results in terms of a latent process of evidence accumulation by fitting fixed and
12 collapsing threshold DDMs to the data from Experiments 1-3. We make the simplifying
13 assumption that the cognitive processes involved in performing the random dot motion task
14 of Experiment 1 and the flash task of Experiments 2 and 3 is approximated by the evidence
15 accumulation process assumed in the DDM. Thus, by comparing whether the fixed or
16 collapsing threshold models provide a more parsimonious account of each experiment we can
17 identify the cognitive processes that were most likely to have generated the data, given the set
18 of models under consideration.

19
20 Based on our earlier literature review, we hypothesize that cue-based manipulations of the
21 SAT will affect the overall amount of evidence required by the decision-makers to commit to
22 a decision, known as boundary separation (Forstmann et al., 2008; Ratcliff & McKoon, 2008;
23 Ratcliff et al., 2016; Wagenmakers et al., 2008). In contrast, we expect that deadline-based
24 manipulations of the SAT will cause dynamic decreases to the threshold throughout the
25 decision process to increase the likelihood of responding before the imposed deadline, known
26 as a collapsing threshold (Cisek et al., 2009; Evans & Hawkins, 2019; Miletic & van Maanen,
27 2019; Thura et al., 2012) . This will allow us to answer the question of whether cue-based
28 and deadline-based manipulations of the SAT are best explained by different parameters of
29 the DDM, within the same participants in the same task.

30 31 **4.1. Models**

32 We fitted the data of each experiment with a set of models that differed in terms of which
33 model parameters were freely estimated across conditions of the experiment and which were
34 constrained to common values (see Table 3). To simplify the model comparison, we note that

1 the mean start point bias was always set to 0, making the assumption that on average
 2 evidence accumulation always begins equidistantly between the boundaries for the two
 3 response options (e.g., see Figure 1 where the accumulation process starts from 0 evidence).
 4 It was not estimated since there was no explicit bias manipulation, however we do allow for
 5 random start point biases across trials (S_z , see below).

6

7 Table 3 shows the parameterization of all models we studied. We describe the set of models
 8 with a naming system that loosely follows Chandrasekaran & Hawkins (2019). The principle
 9 of the naming system is that a model is augmented with a character for each additional
 10 parameter freely estimated across conditions; the characters for each parameter are shown in
 11 the notes to Table 3. Parameters that are freely estimated from data though constrained to the
 12 same value across conditions are not referred to in the model name. For illustration, the
 13 model in the upper row of Table 3 is named f-DDM-vat-SvStSz because it is a fixed
 14 thresholds DDM (f-DDM) that freely estimates the base parameters of drift rate (v), threshold
 15 (a) and non-decision time (t), and across-trial variability parameters for drift rate (S_v), non-
 16 decision time (S_t), and starting point (S_z). By comparison, the model in the final row of Table
 17 3 is named c-DDM-a because it is a collapsing thresholds DDM (c-DDM) that freely
 18 estimates the threshold (a) and the slope of the collapsing threshold (which is encapsulated in
 19 the “c” of “c-DDM”).

20

21 *Table 3. Description of the models fitted to Experiments 1-3*

Model	Free parameters	Constrained parameters	Fixed parameters
f-DDM-vat-SvStSz	$v, T_{er}, \alpha, S_v, S_t, S_z$	—	Z
c-DDM-vat-SvStSz	$v, T_{er}, \alpha, S_v, S_t, S_z, \text{slope}$	—	Z
f-DDM-vat-SvSt	$v, T_{er}, \alpha, S_v, S_t$	—	Z, S_z
c-DDM-vat-SvSt	$v, T_{er}, \alpha, S_v, S_t, \text{slope}$	—	Z, S_z
f-DDM-vat-SvSz	$v, T_{er}, \alpha, S_v, S_z$	—	Z, S_t
c-DDM-vat-SvSz	$v, T_{er}, \alpha, S_v, S_z, \text{slope}$	—	Z, S_t
f-DDM-vat-Sv	v, T_{er}, α, S_v	—	Z, S_z, S_t
c-DDM-vat-Sv	$v, T_{er}, \alpha, S_v, \text{slope}$	—	Z, S_z, S_t
f-DDM-a-Sv	α, S_v	v, T_{er}	Z, S_z, S_t
c-DDM-a-Sv	$\alpha, S_v, \text{slope}$	v, T_{er}	Z, S_z, S_t

c-DDM-a	α , slope	v , T_{er} , S_v	z , S_z , S_t
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1 *Note: Free parameters were estimated independently per condition and participant.*
2 *Constrained parameters were estimated per participant though held to the same value across*
3 *conditions. Fixed parameters were not estimated from the data. ‘v’ stands for drift rate, ‘T_{er}’*
4 *for non-decision time, ‘a’ for threshold, ‘s_v’ for variability in drift rate, ‘z’ for starting point,*
5 *‘s_z’ for variability in the starting point, ‘s_t’ for variability in non-decision time, and ‘slope’*
6 *for the amount of decrease in thresholds.*

7
8 The number of freely estimated parameters in each model for each participant is determined
9 by multiplying the number of parameters listed in the “free parameters” column of Table 3 by
10 the number of conditions in the experiment (4 in Experiments 1 and 2, 6 in Experiment 3)
11 plus the number of parameters listed in the “constrained parameters” column. For example, in
12 model f-DDM-vat-Sv there are 4 (parameters) x 4 (E1/E2) or 6 (E3) + 0 = 16 (E1/E2) or 24
13 (E3) parameters per participant. For c-DDM-vat-Sv, the collapsing thresholds equivalent,
14 there are 20 (E1/2) or 30 (E3) parameters per participant.

15
16 Some model parameters were of particular relevance to our hypotheses. In the collapsing
17 threshold DDMs, the threshold parameter indicates the initial level of response caution
18 (boundary separation at time 0) and the slope indicates how quickly this caution changes as
19 the time since stimulus onset increases (rate of decline). We expect that the cue-based
20 manipulation but not deadline-based manipulation will influence the initial threshold, and we
21 expect that the deadline-based manipulation but not the cue-based manipulation will
22 influence the slope. Therefore, if both hypotheses are supported we expect evidence for a
23 model with collapsing thresholds (any of the c-DDM models). For simplicity, we assume all
24 collapsing thresholds decrease linearly as a function of elapsed decision time, which is a form
25 of collapsing thresholds that is well identified in data (Evans, Trueblood, & Holmes, 2019).
26 For the fixed threshold DDMs, the threshold parameter indicates the general response caution
27 of the participant, which is independent of elapsed decision time. Therefore, if there is
28 support for our hypothesis about cue-based manipulations but not deadline-based
29 manipulations we expect evidence for a model with fixed thresholds (any of the f-DDM
30 models).

31

1 We also considered the across-trial variability parameters of the DDM. Across-trial
2 variability in drift-rate was of particular importance as it plays an important role in allowing a
3 fixed-threshold DDM to capture slow errors (Ratcliff, 1978) which are also predicted by a
4 collapsing thresholds without across-trial variability in the drift rate (Hawkins,
5 Wagenmakers, et al., 2015). As a result, by estimating drift rate variability we create a level
6 playing field in terms of the capacity for collapsing and fixed threshold DDMs to account for
7 slow errors, which were present in the data. If across-trial variability in drift rate is the cause
8 of slow errors then we expect evidence for any of the f-DDM models with S_v , though if slow
9 errors are instead due to collapsing thresholds we expect support for any of the c-DDM
10 models, which may also have an additional contribution from variability in drift rate. We also
11 tested whether the additional flexibility of across-trial variability in starting point and/or non-
12 decision time accounted for unique variance in the data not already explained by fixed or
13 collapsing thresholds with or without drift rate variability. If this additional flexibility is
14 required to account for the data then we expect to support models with S_t and/or S_t .⁷ We also
15 tested much more constrained models by enforcing the same drift rate and non-decision time
16 across conditions (f-DDM-a- S_v , c-DDM-a- S_v). Comparison of f-DDM-a- S_v with c-DDM-a
17 (without drift rate variability) allowed us to test the unique contribution of the drift rate
18 variability parameter and its potential substitutability with the collapsing threshold parameter.
19

20 **4.2. Fitting Procedure.**

21 We followed the parameter estimation routines of Hawkins, Forstmann, et al. (2015). We
22 used Monte Carlo simulation with 10,000 samples per experimental condition during
23 parameter estimation, which was conducted by quantile maximum probability estimation. To
24 ensure the comparison between the models was fair, we used the same simulation-based
25 method for parameter fitting of the DDM with fixed thresholds. We set the diffusion
26 coefficient ($s=.1$) as a scaling parameter and fitted the DDM to RT in seconds. In addition,
27 we verified that the fixed and collapsing threshold models recovered almost all of the
28 estimated parameters well (yet, the drift-rate variability parameter recovered less well than
29 other parameters). For details of the parameter recovery see supplementary materials, and for
30 a more complete treatment of parameter recovery in collapsing threshold models see Evans,
31 Trueblood, & Holmes, (2019).

⁷ When interpreting these results, the reader should take into account that estimation of across-trial variability parameters can be challenging in some contexts (see for example: Boehm et al., 2018).

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The best-fitting parameters for all models listed in Table 2 were independently estimated for each participant in each experiment, which makes the model application consistent with the within-subject design of the three experiments. Parameters were estimated through the Differential Evolution optimization algorithm (Ardia et al., 2011) with a maximum of 1000 iterations.

4.3. Model comparison and model fit

To assess which models provided the most parsimonious account of the data – that is, the best balance between goodness-of-fit to data and model flexibility – we used the Akaike Information Criterion (AIC), along with its correction for small samples (AICc), and the Bayesian Information Criterion (BIC). These three metrics are used as a standard practice in model comparison (Akaike, 1974; Schwarz, 1978; see also Heathcote, Brown, & Wagenmakers, 2015). The three measures are based on the quantile maximum log-likelihood of the fitted models and reward goodness-of-fit but penalize for extra free parameters, with different complexity penalties across the three metrics. Lower values indicate more parsimonious accounts of data than higher values⁸.

Table 4 shows the model comparison outcomes. All three experiments provided the most support for the same model: collapsing thresholds with across-trial variability in drift rate (c-DDM-vat-Sv). For models that did not include across-trial variability in starting point and non-decision time, the collapsing thresholds version of each model tended to provide the best explanation of the data, though not in all cases. However, for models that did include those sources of additional variability, the fixed thresholds models tended to outperform the collapsing thresholds models, though again not in all cases. Nevertheless, there was no combination of the variability parameters in the fixed thresholds model that provided a better explanation of the data than the best collapsing thresholds model. Generally, the models that allowed drift rates and non-decision times to vary across conditions showed a much better performance than those in which these parameters were constrained to the same value across conditions, in spite of the increased number of free parameters. Interestingly, omitting drift-rate variability in c-DDM-a substantially worsened performance of the collapsing model,

⁸ We arrived at the same conclusions by performing chi-square tests on model deviances based on average log-likelihoods.

1 which underscores the fact that drift-rate variability makes a unique contribution to the model
2 and cannot be substituted by the slope parameter.⁹ For the remainder of the results we explore
3 the performance of the best performing collapsing threshold model (c-DDM-vat-Sv) and best
4 performing fixed threshold model (f-DDM-vat-Sv). For simplicity, we refer to these models
5 simply as the collapsing and fixed threshold models rather than repeatedly naming their
6 precise parameterizations.

7

⁹ Another way to establish the unique contribution of the slope parameter is to look at correlations among the estimated model parameters. For example, in Experiment 3, the slope parameter did not correlate with the drift-rate variability parameter; a finding which points to the unique contribution of each of these two parameters in explaining the data (see supplementary materials: Figure 15 and Table 1).

1 *Table 4. Model comparison between fixed and collapsing threshold DDMs.*

Experiment	Model	# of parameters	AIC	AICc	BIC
Experiment 1	f-DDM-vat-SvStSz	576 (24)	86179	86215	90704
	c-DDM-vat-SvStSz	672 (28)	87075	87124	92354
	f-DDM-vat-SvSt	480 (20)	85905	85930	89676
	c-DDM-vat-SvSt	576 (24)	87092	87128	91617
	f-DDM-vat-SvSz	480 (20)	86912	86937	90683
	c-DDM-vat-SvSz	576 (24)	87035	87071	91560
	f-DDM-vat-Sv	384 (16)	87028	87045	90045
	c-DDM-vat-Sv	480 (20)	85805	85831	89577
	f-DDM-a-Sv	240 (10)	343907	343911	345869
	c-DDM-a-Sv	336 (14)	161917	161929	164557
	c-DDM-a	264 (11)_	457219	457177	459293
Experiment 2	f-DDM-vat-SvStSz	576 (24)	92089	92125	96613
	c-DDM-vat-SvStSz	672 (28)	92520	92569	97797
	f-DDM-vat-SvSt	480 (20)	91991	92016	95761
	c-DDM-vat-SvSt	576 (24)	92349	92385	96873
	f-DDM-vat-SvSz	480 (20)	92658	92683	96428
	c-DDM-vat-SvSz	576 (24)	92309	92345	96833
	f-DDM-vat-Sv	384 (16)	92417	92433	95433
	c-DDM-vat-Sv	480 (20)	91661	91685	95430
	f-DDM-a-Sv	240 (10)	228937	228943	230822
	c-DDM-a-Sv	336 (14)	204389	204401	207028
	c-DDM-a	264 (11)_	477437	477445	479511
Experiment 3	f-DDM-vat-SvStSz	864 (36)	88386	88471	95143
	c-DDM-vat-SvStSz	1008 (42)	89081	89198	96964
	f-DDM-vat-SvSt	720 (30)	88125	88184	93755
	c-DDM-vat-SvSt	864 (36)	88801	88886	95557
	f-DDM-vat-SvSz	720 (30)	89538	89597	95169
	c-DDM-vat-SvSz	864 (36)	88885	88971	95642

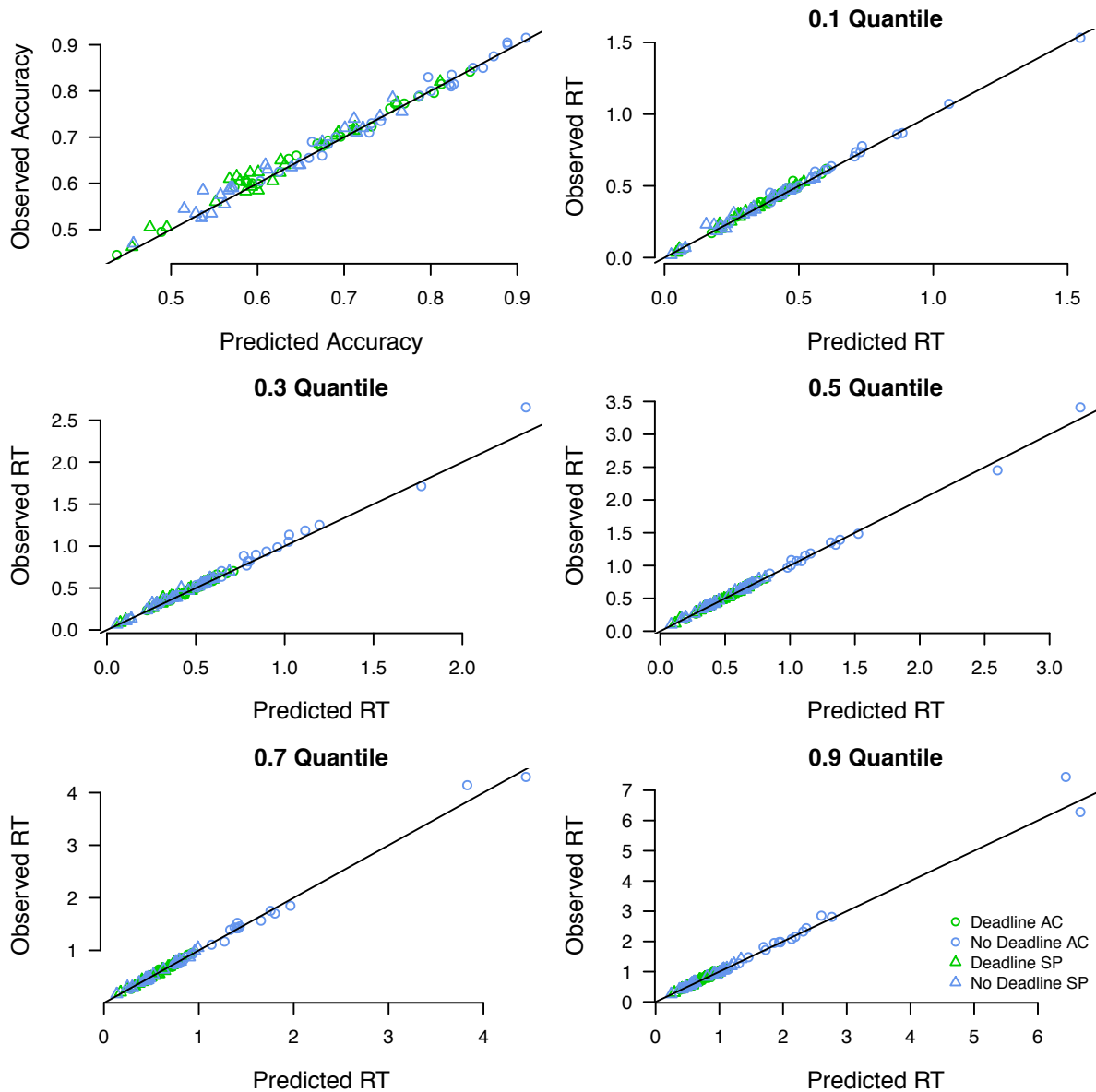
f-DDM-vat-Sv	576 (24)	89147	89184	93651
c-DDM-vat-Sv	720 (30)	87800	87859	93431
f-DDM-a-Sv	336 (14)	148968	148981	151596
c-DDM-a-Sv	480 (20)	134873	134899	138627
c-DDM-a	360 (15)	490338	490338	493153

1 *Note: Models that are preferred according to each model selection metric are presented in*
2 *bold per Experiment. The number of parameters refers to the total number estimated across*
3 *all participants (in parentheses, the number of estimated parameters per participant is also*
4 *given). Raw AIC, AICc and BIC values are given rounded to nearest whole number.*

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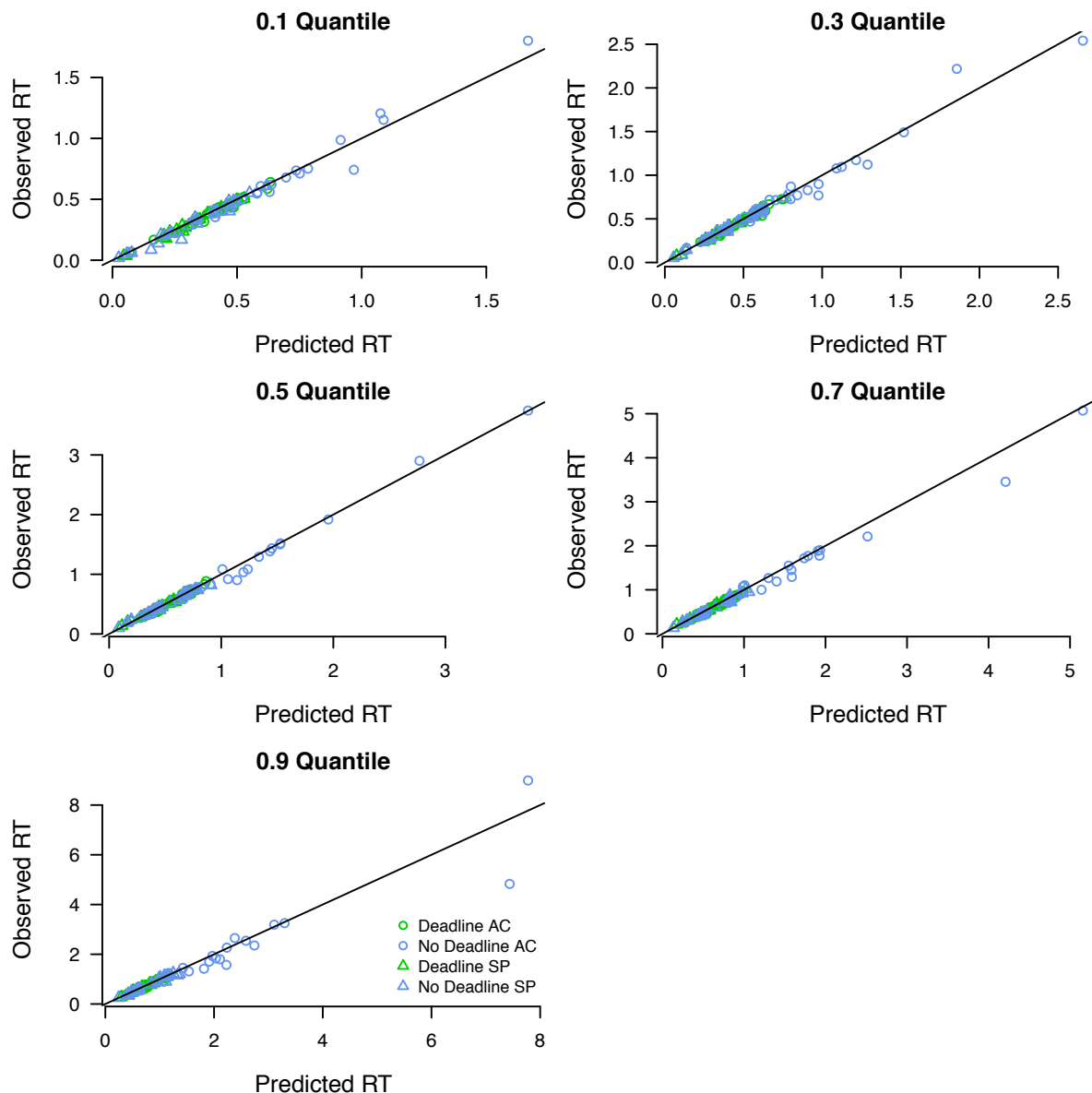
6 To provide absolute model fit diagnostics, the fit of the preferred collapsing threshold model
7 is shown in Figures 2 and 3, taking Experiment 2 as an example. The model provides a very
8 good account of the data, with correlations between observed and predicted data (RT
9 quantiles and accuracy) greater than 0.97. The fit of the same model to Experiments 1 and 3
10 was equally good (see supplementary materials: Figures 3-6). In Experiment 1, the model fit
11 strongly correlated with observed data in correct responses (above 0.97) but error responses
12 exhibited higher variability, especially in the conditions without a deadline (correlations
13 above 0.70). Higher variability in fitting error responses is expected because of the fewer
14 errors made in no deadline conditions; a phenomenon observed in model fits of other tasks as
15 well (Palminteri, Wyart, & Koechlin, 2017). In Experiment 3, the collapsing threshold model
16 slightly underestimated accuracy in the early deadline condition though all correlations
17 between observed and predicted values were above 0.95 for both error and correct responses.

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Figure 2. Fit of model *c-DDM-vat-Sv* to the correct responses of Experiment 2. Observed vs. predicted accuracy and quantile RTs per participant and condition are shown. RTs are given for the 0.1, 0.3, 0.5, 0.7 and 0.9 quantiles. Lines represent the identity function.



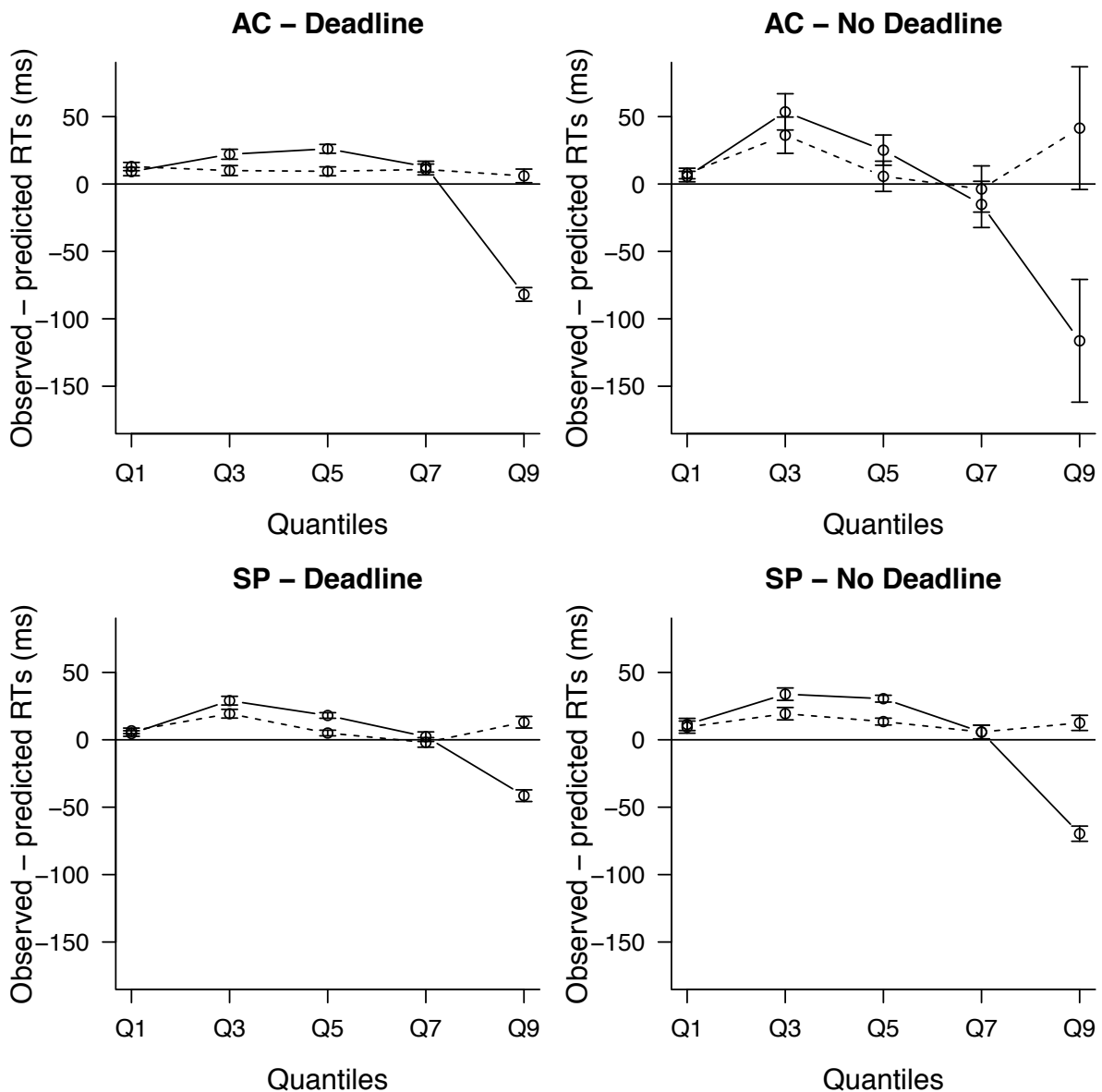
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2 *Figure 3. Fit of model c-DDM-vat-Sv to the error responses of Experiment 2. Observed vs.*
 3 *predicted quantile RTs per participant and condition are shown. RTs are given for the 0.1,*
 4 *0.3, 0.5, 0.7 and 0.9 quantiles. Lines represent the identity function.*

5

6 To understand why the collapsing threshold model was preferred over its nearest fixed
 7 thresholds competitor (f-DDM-vat-Sv), we explored which quantitative patterns in data the
 8 fixed thresholds model missed. The goodness of fit to data of the fixed threshold model had
 9 some similar strengths and weaknesses to the collapsing threshold model: higher variability
 10 in error responses and underestimation of the observed accuracy in the Early Deadline
 11 condition of Experiment 3 (see Figures 7-12 of supplementary materials). However, the fixed
 12 threshold model also tended to underestimate the RT distributions in all quantiles, especially

1 in Experiments 1 and 3. This result is shown more completely in Figure 4. The fixed
 2 threshold model underestimates the central body of the RT distributions (.3 and .5 quantiles)
 3 but heavily overestimates the tails (.9 quantile .9). This happens because the fixed threshold
 4 model predicts heavier tailed distributions than what was observed in data. To predict shorter
 5 tailed distributions, the fixed thresholds model underpredicts the main body of the RT
 6 distributions. The collapsing threshold model appears to fit the data better. Similar patterns
 7 were observed in the other two experiments; see supplementary materials Figures 13-14.
 8



9
 10 *Figure 4. Deviation between observed and predicted RTs for the 0.1, 0.3, 0.5, 0.7 and 0.9*
 11 *quantiles of the RT distribution separately for each condition in Experiment 2, averaged*

1 *across participants. Continuous lines indicate the fixed threshold model and dashed lines*
2 *indicate the collapsing threshold model. Bars represent standard errors.*

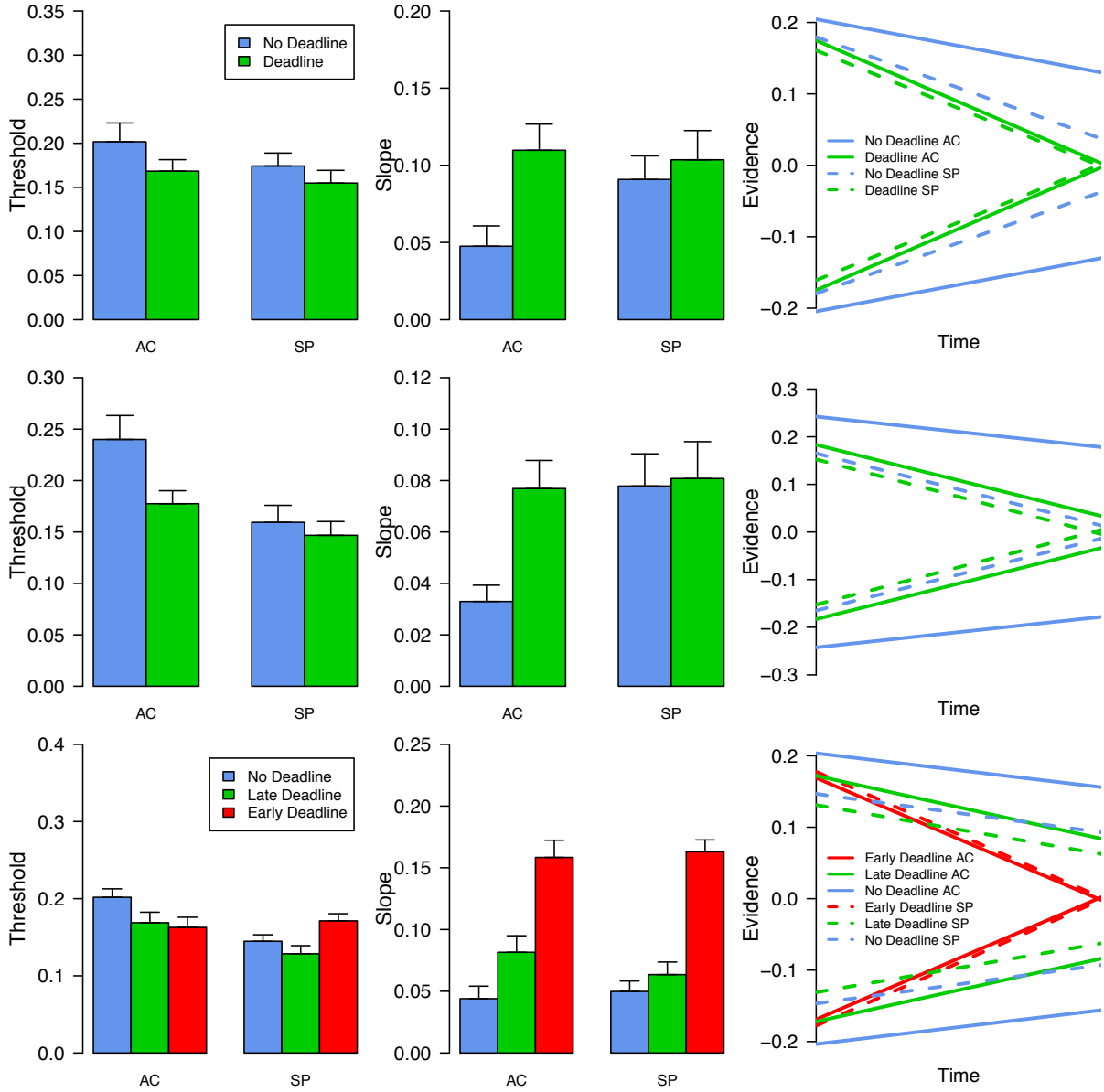
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4 **4.4. Model parameters**

5 We now evaluate how the parameters of the best model of the data (i.e. the collapsing
6 threshold model) changed across the conditions of the three Experiments. Figure 5 and 6
7 provide a graphical presentation of the model parameters. Figure 5 presents the model
8 parameters of greatest interest to our hypotheses: the initial value of the response threshold,
9 and the rate of decline in that threshold as the time from stimulus onset increases. Figure 6
10 presents the rest of the parameters: drift-rate, drift-rate variability and non-decision time.

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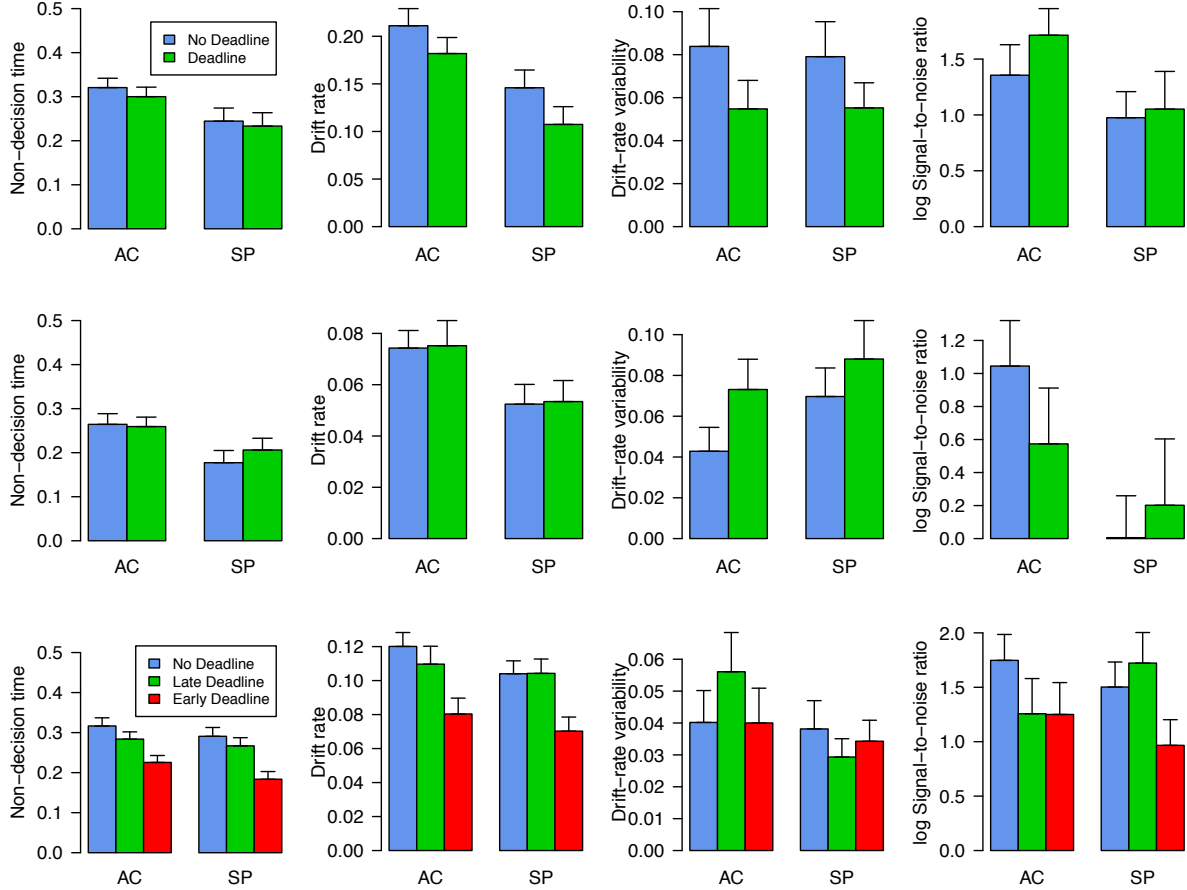
2 *Figure 5. Mean slope and threshold parameters of the collapsing thresholds model. Top row:*
 3 *Experiment 1. Middle row: Experiment 2. Bottom row: Experiment 3. Means are given with*
 4 *standard errors. ‘AC’ and ‘SP’ stands for ‘accuracy’ and ‘speed’ respectively. The right-*
 5 *hand column provides a mean representation of the threshold and slope parameters.*

6

7 Across all experiments, the response thresholds declined to a significantly greater extent in
 8 trials with deadlines than trials without deadlines (E1 - $F(1,23)=9.97$, $p=0.004$, $\eta_G^2=0.05$; E2 -
 9 $F(1,23)=5.20$, $p=0.032$, $\eta_G^2=0.04$; E3 - $F(1,46)=58.75$, $p<0.001$, $\eta_G^2=0.45$). In contrast, the
 10 thresholds declined at different rates for speed-focused relative to accuracy-focused trials
 11 only in Experiment 2 ($F(1,23)=5.75$, $p=0.024$, $\eta_G^2=0.04$), not Experiments 1 or 3 (E1 -
 12 $F(1,23)=1.33$, $p=0.260$, $\eta_G^2=0.01$; $BF_{10}=0.43$; E3 - $F(1,23)=0.13$, $p=0.718$, $\eta_G^2<0.01$;

1 BF₁₀=0.18). There was also no interaction between the cue-based and deadline-based
2 manipulation on the slope parameter in Experiments 1 and 3 (E1 - $F(1,23)=3.97$, $p=0.058$,
3 $\eta_G^2=0.02$; BF₁₀=0.99; E3 - $F(1,46)=1.10$, $p=0.339$, $\eta_G^2=0.01$; BF₁₀=0.24), though there was a
4 significant interaction in Experiment 2 ($F(1,23)=6.19$, $p=0.020$, $\eta_G^2=0.03$). As seen in Figure
5 5, this interaction was driven by the shallow decline in the threshold in the accuracy - no
6 deadline condition compared to the steeper decline in the remaining three conditions. It is
7 worth noting that a similar trend was present in Experiment 1 though the pattern was not
8 statistically significant.

9
10 In contrast, the initial value of the threshold – an indicator of the overall level of response
11 caution – was significantly greater in accuracy-focused compared to speed-focused trials
12 across all three experiments (E1 - $F(1,23)=5.63$, $p=0.026$, $\eta_G^2=0.01$; E2 - $F(1,23)=12.16$,
13 $p=0.001$, $\eta_G^2=0.10$; E3 - $F(1,23)=12.65$, $p=0.001$, $\eta_G^2=0.07$). The initial threshold was also
14 greater in trials without a deadline compared to with a deadline in Experiments 1 and 2 (E1 -
15 $F(1,23)=7.27$, $p=0.012$, $\eta_G^2=0.02$; E2 - $F(1,23)=6.60$, $p=0.017$, $\eta_G^2=0.05$), but not Experiment
16 3 ($F(1,46)=2.61$, $p=0.084$, $\eta_G^2=0.03$; BF₁₀=0.65). The interaction followed a similar pattern;
17 not significant in Experiments 1 and 2 (E1 - $F(1,23)=0.34$, $p=0.563$, $\eta_G^2<0.01$; BF₁₀=0.30; E2
18 - $F(1,23)=3.38$, $p=0.078$, $\eta_G^2=0.02$; BF₁₀=0.92) though significant in Experiment 3
19 ($F(1,46)=5.78$, $p=0.005$, $\eta_G^2=0.06$). The interaction was driven by the early deadline – speed
20 condition, which showed higher levels of threshold than expected. This was likely because
21 this condition had a very large slope relative to the other deadline conditions, so to
22 compensate the initial threshold was set to a higher value.



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Figure 6. Mean non-decision time, drift rate and drift-rate variability parameters of the collapsing thresholds model along with the log drift-rate – log drift-rate variability (denoted as “signal-to-noise ratio”). Top row: Experiment 1. Middle row: Experiment 2. Bottom row: Experiment 3. Means are given with standard errors. ‘AC’ and ‘SP’ stands for ‘accuracy’ and ‘speed’ respectively.

For the rest of the model parameters (Figure 6), we observed that the parameter of non-decision time was slower in the accuracy-focused trials than in speed-focused ones in Experiments 1 and 2 but not in Experiment 3 ($F(1,23)=11.41$, $p=0.002$, $\eta_G^2=0.07$; E2 - $F(1,23)=10.05$, $p=0.004$, $\eta_G^2=0.07$; E3 - $F(1,23)=2.66$, $p=0.116$, $\eta_G^2=0.02$; $BF_{10}=0.60$). In addition, non-decision time was faster in deadline conditions but only in Experiment 3 while the rest of the Experiments did not show significant differences (E1 - $F(1,23)=2.14$, $p=0.156$, $\eta_G^2<0.01$; $BF_{10}=0.25$; E2 - $F(1,23)=0.46$, $p=0.502$, $\eta_G^2<0.01$; E3 - $F(1,46)=25.85$, $p<0.001$, $\eta_G^2=0.16$). No interaction was observed (E1 - $F(1,23)=0.13$, $p=0.719$, $\eta_G^2<0.01$; $BF_{10}=0.30$; E2 - $F(1,23)=1.25$, $p=0.274$, $\eta_G^2<0.01$; $BF_{10}=0.31$; E3 - $F(1,46)=0.38$, $p=0.680$, $\eta_G^2<0.01$; $BF_{10}=0.14$).

1
2 The drift rate parameter – the rate perceptual information is accumulated by the decision-
3 maker – showed a clear pattern according to which it was higher in across accuracy-focused
4 than speed-focused trials (E1 - $F(1,23)=20.85$, $p<0.001$, $\eta_G^2=0.12$; E2 - $F(1,23)=14.34$,
5 $p<0.001$, $\eta_G^2=0.07$; E3 - $F(1,23)=4.28$, $p=0.049$, $\eta_G^2=0.01$) as well as in trials without
6 deadlines than in trials with deadlines in two out of the three Experiments (E1 -
7 $F(1,23)=10.67$, $p=0.003$, $\eta_G^2=0.03$; E2 - $F(1,23)=0.02$, $p=0.870$, $\eta_G^2<0.01$; $BF_{10}=0.21$; E3 -
8 $F(1,46)=15.53$, $p<0.001$, $\eta_G^2=0.12$). Additionally no interaction was observed between these
9 two factors (E1 - $F(1,23)=0.15$, $p=0.700$, $\eta_G^2<0.01$; $BF_{10}=0.29$; E2 - $F(1,23)<0.001$, $p=0.992$,
10 $\eta_G^2<0.01$; $BF_{10}=0.29$; E3 - $F(1, 46)=0.37$, $p=0.691$, $\eta_G^2<0.01$; $BF_{10}=0.13$).

11
12 On the other hand, the drift-rate variability parameter showed mixed results (for a
13 relationship between the drift-rate and drift-rate variability see Figure 6: last right column): it
14 was higher in conditions without deadlines in Experiment 1 but it was lower for deadline
15 conditions in Experiment 2, while no significant difference was found for Experiment 3 (E1 -
16 $F(1,23)= 5.27$, $p=0.031$, $\eta_G^2=0.13$; E2 - $F(1, 23)=5.35$, $p=0.029$, $\eta_G^2<0.02$; E3 - $F(1,46)=0.16$,
17 $p=0.850$, $\eta_G^2<0.01$; $BF_{10}=0.13$). Furthermore, that model parameter did not significantly
18 change across speed-focused vs. accuracy-focused trials (E1 - $F(1,23)=0.03$, $p=0.866$,
19 $\eta_G^2<0.01$; $BF_{10}=0.21$; E2 - $F(1,23)=2.17$, $p=0.154$, $\eta_G^2<0.01$; $BF_{10}=0.49$; E3 - $F(1,23)=1.94$,
20 $p=0.176$, $\eta_G^2=0.01$; $BF_{10}=0.51$). No interaction between the two factors was observed in the
21 drift-rate variability parameter (E1 - $F(1,23)=0.03$, $p=0.856$, $\eta_G^2<0.01$; $BF_{10}=0.29$; E2 -
22 $F(1,23)=0.11$, $p=0.734$, $\eta_G^2<0.01$; $BF_{10}=0.30$; E3 - $F(1,46)=1.94$, $p=0.176$, $\eta_G^2=0.01$;
23 $BF_{10}=0.26$).

24
25 Taken together, the deadline-based manipulations were most consistently associated with the
26 slope parameter of the collapsing threshold model such that response deadlines induced
27 steeper slopes than no deadline conditions in Experiment 1 and 2, with the same pattern
28 observed across the three deadline levels in Experiment 3. The threshold parameter, on the
29 other hand, was most consistently associated with the cue-based manipulation such that
30 speed-focused trials reduced the response threshold relative to accuracy-focused trials. This
31 result aligns with a large body of literature (Evans et al., in press; Forstmann et al., 2008;
32 Frazier & Yu, 2007; Hawkins, Wagenmakers, et al., 2015; Rae, Heathcote, Donkin, Averell,
33 & Brown, 2014; Ratcliff & McKoon, 2008; Van Maanen et al., 2011; Wagenmakers et al.,

1 2008). In addition, trials with deadlines and with speed-focused instructions produced lower
2 drift-rates than trials without deadlines or with accuracy-focused instructions. However, we
3 found mixed results for the association of the non-decision time parameter with deadline
4 conditions (the non-decision time parameter was faster in conditions with deadlines only in
5 Experiment 3 in line with previous studies, e.g. Murphy, Boonstra, & Nieuwenhuis, 2016) or
6 the association of the drift-rate variability with deadline conditions (drift-rate variability was
7 higher for trials with deadlines only in Experiment 2).

9 **5. General discussion**

10 We have provided evidence that deadline-based and cue-based manipulations of the speed-
11 accuracy trade-off have different psychological effects on latent decision making processes.
12 Our results indicate that cue-based manipulations affect the general level of response caution
13 with which people make perceptual decisions. Throughout the course of a decision, this
14 overall level is subject to dynamic changes due to a potential pressure to respond. Such time
15 pressure can be experimentally induced through deadlines, but is less sensitive to pre-
16 stimulus cues. These results are in line with previous empirical investigations of deadline and
17 instruction effects on human RT and accuracy data (Forstmann et al., 2010, 2008; Frazier &
18 Yu, 2007; Karşilar et al., 2014; Miletic & van Maanen, 2019; Pike, 1968; Pike & Dalgleish,
19 1982; Van Maanen et al., 2011; Van Zandt et al., 2000).

21 The differences between the overall level of caution and how it changes throughout the
22 course of a decision is well explained within the theoretical framework of evidence
23 accumulation models (such as the DDM) that incorporate collapsing thresholds. We found
24 that the best explanation of the data assigned the effect of a cue-based manipulation of the
25 SAT to the overall level of the decision threshold, and the effect of a deadline-based
26 manipulation of the SAT to dynamically collapsing thresholds. The model also assumed that
27 mean drift rate, drift rate variability and non-decision time changed across conditions. This
28 model is preferable for three reasons. First, it provides a coherent conceptual account of the
29 cognitive mechanisms triggered by time pressure manipulations during perceptual decision-
30 making. Second, it is consistent with the differential effects of cue-based and deadline-based
31 manipulations observed in the behavioral data. Third, it is able to better capture the choice
32 and RT patterns in the behavioral data.

1 An alternative to a collapsing threshold model that is sometimes tested is the so-called Fast
2 Guess model by Ollmann (Falmagne, 1968; Ollman, 1966; van Maanen, Couto, & Lebreton,
3 2016; van Maanen, de Jong, & van Rijn, 2014). This model proposes that participants might
4 switch to a guessing strategy to make faster responses. Such a strategy would indeed speed
5 up behavior at the expense of accuracy, thus explaining the SAT. If participants guessed on a
6 higher proportion of trials when they are cued for speed than when they are cued for accuracy
7 the response time distributions should show signatures of mixture distributions. In previous
8 work, we found no evidence for the Fast Guess model in cue-based SAT data (van Maanen,
9 2016). Re-analyzing the data of Experiment 3 of the current paper confirms this result for
10 deadline-based SAT (see supplementary materials). A change in the proportion of guess
11 responses due to a deadline therefore does not seem likely. For this reason, we did not
12 explore this class of models further. Nevertheless, for future research it may be worth
13 investigating the issue of mixtures of decision-making processes in the context of the DDM
14 (cf. Ratcliff, 2006).

15
16 There are a number of practical and theoretical implications of our results. First, we showed
17 that deadline-based and cue-based manipulations do not induce a speed-accuracy trade-off in
18 the same way. Because the two manipulations target qualitatively different cognitive
19 processes, the experimenter's choice between the two methods should be carefully
20 considered in studies aimed at experimentally inducing a speed-accuracy trade-off. Second,
21 we provided evidence in favor of the use of accumulation models with collapsing bounds for
22 the study of time pressure effects in perceptual decision-making. Collapsing threshold models
23 may provide a more complete representation of how humans respond when faced with
24 particular types of time pressure. Third, we found mixed support for the necessity of
25 incorporating variability parameters in the DDM to explain behavior under time pressure:
26 models without non-decision time and starting-point variability parameters explained our
27 data better (in contrast to the findings of Rae et al., 2014), but variability in the drift-rate was
28 necessary (in line with Voskuilen et al., 2016). These results indicate the need for further
29 research on the set of variability parameters that are necessary to explain the cognitive
30 processes involved in decisions under time pressure. We note that while our results have
31 implications for a range of tasks and evidence accumulation models of perceptual decision-
32 making, future investigations should evaluate whether the same computational principles of
33 the SAT described in this study generalize to more complex forms of decision-making (e.g.,
34 value-based choices).

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Our results regarding decision-making under time pressure are in line with recent literature on the topic. First, we provide empirical evidence supporting Frazier and Yu's (2008) thesis, which predicted that when humans are faced with deadlines, decision-makers require less evidence to commit to a decision as time passes. This is in line with previous work suggesting that decisions for which not enough evidence can be obtained in the allotted time are characterized by collapsing thresholds (Boehm, Hawkins, Brown, van Rijn, & Wagenmakers, 2016; Evans et al., in press; Hawkins, Forstmann, et al., 2015; Hawkins, Wagenmakers, et al., 2015; Miletic & van Maanen, 2019; Murphy, Boonstra, & Nieuwenhuis, 2016). It is important to note, however, that our modeling analyses did not address the question of whether people followed an optimal or a suboptimal decision policy. This remains a matter of research to be established in the future, though the interested reader is referred to Karşilar et al. (2014) for an earlier comprehensive treatment of the topic.

In the evidence accumulation models we studied here, we accounted for deadline-based time pressure with a linearly collapsing thresholds for reasons of simplicity. However, many different functional forms of this kind of urgency signal have been proposed, and the current study did not aim to differentiate between those. In particular, some researchers have argued for an additive (Cisek et al., 2009) or multiplicative temporal signal (Drugowitsch, Moreno-Bote, Churchland, Shadlen, & Pouget, 2012; Frazier & Yu, 2008) on the accumulation process (i.e., the drift rate), while others have argued for a concave collapsing threshold (Ratcliff & Frank, 2012). However, in terms of response time and accuracy distributions, these proposals are difficult to disentangle, and for that reason we chose the simplest possible functional form with the primary aim of differentiating between conditions without an urgency signal (i.e., a fixed threshold) and conditions with urgency in a model specification that is well-identified in data (Evans et al., 2019). Although a DDM with linearly collapsing thresholds was able to capture many of the empirical patterns elicited by deadline-based time pressure (yet not perfectly, see e.g. Figure 4), it may be that evidence accumulation models with more complex functional forms for the decreasing threshold will further improve the explanation of performance under these conditions. Therefore, further research is required to establish under which conditions more complex functional forms are necessary to explain the behavioral patterns, which might also include other SAT manipulations that do not explicitly use deadlines (e.g., Palestro, Weichart, Sederberg, & Turner, 2018).

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